# FANUC Robot M-1000iA



#### **Features**

FANUC Robot M-1000iA is a large and heavy payload robot with wide motion range and 1000kg payload capacity.

- M-1000iA has a J3 arm which can stand upright above and rotate backwards of the robot. The wide motion range realizes a large operation area including above and behind the robot, therefore M-1000iA can adapt various layout environments.
- M-1000iA has 1000kg payload capacity and a strong wrist. M-1000iA can handle large and heavy workpieces such as battery units of EVs, long building structures, etc. The wrist has IP67-equivalent resistance to environmental conditions (dust and dips) and can be used in harsh environments with confidence.
- Due to a high rigidity design, M-1000 $\dot{t}$ A is available for machining such as drilling.
- Tablet TP, which has a large touch panel and an user-friendly intuitive interface, and traditional iPendant are available as a teaching device.
- *i*RVision and various intelligent features are available. These enable to build robot systems flexibly.

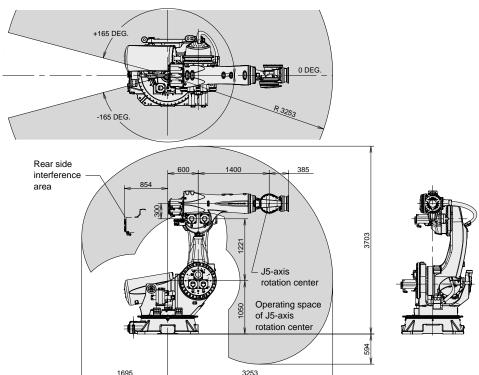
## Application Example



**Battery Unit Handling** 

#### Operating space

## M-1000*i*A



### **Specifications**

Model		M-1000 <i>İ</i> A
Туре		Articulated Type
Controlled axes		6 axes (J1, J2, J3, J4, J5, J6)
Reach		3253 mm
Installation		Floor
Motion range (Maximum Speed) Note 1)	J1 axis rotation	330°(60°/s) 5.76 rad (1.05 rad/s)
	J2 axis rotation	145°(50°/s) 2.53 rad (0.87 rad/s)
	J3 axis rotation	260°(50°/s) 4.54 rad (0.87 rad/s)
	J4 axis wrist rotation	720°(70°/s) 12.57 rad (1.22 rad/s)
	J5 axis wrist swing	240°(70°/s) 4.19 rad (1.22 rad/s)
	J6 axis wrist rotation	720°(85°/s) 12.57 rad (1.48 rad/s)
Max. load capacity at wrist		1000 kg
Max. load capacity at J2 base		550 kg
Max. load capacity on J3 casing		50 kg
Allowable load moment at wrist	J4 axis	8800 N⋅m 898 kgf⋅m
	J5 axis	8800 N·m 898 kgf·m
	J6 axis	5800 N⋅m 592 kgf⋅m
Allowable load inertia at wrist	J4 axis	1750 kg·m² 17857 kgf·cm·s²
	J5 axis	1750 kg·m² 17857 kgf·cm·s²
	J6 axis	840 kg·m² 8571 kgf·cm·s²
Drive method		Electric servo drive by AC servo motor
Positioning accuracy Note 2)		± 0.10 mm
Mass Note 3)		5300 kg
Installation environment		Ambient temperature : 0 to 45°C  Ambient humidity : Normally 75 %RH or less (No condensation allowed)  Short term (within one month) Max. 95 %RH or less  (No condensation allowed)  Vibration acceleration : 4.9 m/s² (0.5G) or less
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Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Compliant with ISO 9283.

Note 3) Without controller.

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